



Detecting
heavy hitters

Gołębiewski,
Kutyłowski²,
Zagórski

Problem

Overview

Hash
intersection

Phase 1

Phase 2

Phase 3

Experiments

Attacks

Detecting heavy-hitters in a P2P network

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P2P networks

ideas and advantages

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P2P architecture

no central control: self-organization

dynamic: a peer can join and leave the network,
nevertheless the network works properly

distributed memory: information spread among the peers,
allocation usually with distributed hash tables



P2P networks

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nevertheless the network works properly

distributed memory: information spread among the peers,
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Advantages

- 1 global scale network
- 2 small administration overhead, no manual work
- 3 efficient communication framework
- 4 cheap
- 5 resilient to faults



Heavy hitter

unfair use of P2P networks

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Normal user

- a few queries, a few downloads
- contribution proportional to usage



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unfair use of P2P networks

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Normal user

- a few queries, a few downloads
- contribution proportional to usage

Heavy hitter

- many queries, many downloads,
unfair use of databases
- crawlers
- parasite networks stealing data from P2P and offering them elsewhere



Heavy hitter

goal

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Detection

- detect P2P nodes that are using the network unfairly
- detect the nodes that **contact a fraction of all nodes**



Heavy hitter

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Detection

- detect P2P nodes that are using the network unfairly
- detect the nodes that **contact a fraction of all nodes**

Limitations

- must be a fully distributed solution, no central control
- low communication overhead



Algorithm overview

idea

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Math background idea

exponential growth within $\frac{1}{2} \log n$ steps:

- 1 from $\sqrt{n}$ to n
- 2 from 1 to only $\sqrt{n}$

Algorithmic idea

- give enough time ($\frac{1}{2} \log n$) for key information to disseminate to all nodes
- but not enough time to disseminate noise



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Input

Each node A holds a list A_L of all nodes that have requested some service from A .



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Each node A holds a list A_L of all nodes that have requested some service from A .

Phase 1

Each node A fetches a small random sublist of B_L of a random B and computes its intersection with A_L (*short list*)



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Phase 1

Each node A fetches a small random sublist of B_L of a random B and computes its intersection with A_L (*short list*)

Phase 2

- 1 the short lists are disseminated.
- 2 a node merges its own short list and the lists received.



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Phase 1

Each node A fetches a small random sublist of B_L of a random B and computes its intersection with A_L (*short list*)

Phase 2

- 1 the short lists are disseminated.
- 2 a node merges its own short list and the lists received.

Phase 3

- 1 each node inspects some number of short lists
- 2 a node considered heavy hitter if on most of these list



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What happens with a heavy hitter that appears on a fraction α of all lists?

phase 1 if the list has size m and sublists have size k , then it appears on a random sublist with pbb

$$\alpha^2 \cdot \frac{k}{m}$$

i.e. some fraction has the heavy hitter on the short lists

phase 2 heavy hitter disseminated back to almost all lists

phase 3 just checking a few lists to exclude noise entries (i.e. honest peers)



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What happens with an honest peer S that used K servers

phase 1 if the list have size m and sublists have size k , then it appears on a random sublist with pbb

$$\left(\frac{K}{m}\right)^2 \cdot \frac{k}{m}$$

i.e. only incidentally a short list may contain S

phase 2 the number of list containing S grows but still not to a constant fraction of all lists

phase 3 during checking very unlikely that majority of lists contain P



Hash intersection

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Given:

- peer A holds a big list A_L
- peer B holds a small list B_R

Find intersection of A_L and B_R ,
but minimize communication.

Simple solution

- B sends B_R to A .
- A computes the intersection.

if the intersection is small, this might be a waste of
communication



Hash intersection mechanism

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Round 1

- 1 each entry in B_R hashed (keyed hash)
- 2 each hash truncated to l_1 bits
- 3 the list of truncated hashes sent to A
- 4 A responds with a bitvector stating which elements from B_R are not in A for sure:
i.e. which truncated entries correspond to no truncated hash computed for A_L



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Round 2

repeat with the candidates left, with a new hash function and truncation to l_2 bits

Round 3,...

...



Hash intersection

parameter choice

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Optimization

- find the optimal number of rounds, and the lengths $l_1, l_2, \dots$
- formulas derived, numerical estimation of minima possible in practical situations



Hash intersection

choice of parameters

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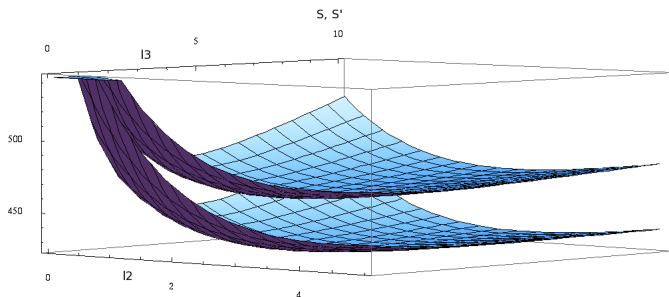
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The expected communication complexity in case of 3 rounds algorithm and honest users (S - smaller values) and heavy hitter (S' - bigger values) for $k = 30$, $m = 1024$, $l_1 = 12$, address space $N = 2^{30}$.



Hash intersection

choice of parameters

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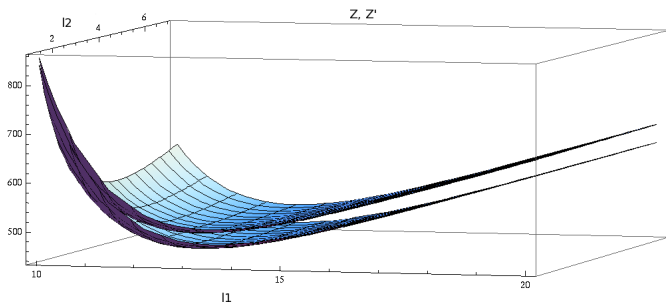
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The expected communication complexity in case of 2 rounds algorithm and honest users (Z - smaller values) and heavy hitter (Z' - bigger values) for $k = 30, m = 1024, N = 2^{30}$.



Hash intersection

advantages

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the optimal choice of parameters l_1, l_2, l_3 , “c.c” denotes expected communication complexity (respectively, S, S', Z and Z'), “rel. c.c.” denotes, respectively, T_3, T_3', T_2, T_2' :

case	l_1	l_2	l_3	c.c.	rel. c.c
$r = 3$ no h.h.	12	2	4	425	0.472
$r = 3$ with h.h.	12	2	4	462	0.513
$r = 2$ no h.h.	12	4	-	441	0.490
$r = 2$ with h.h.	12	4	-	474	0.527



Phase 1

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1 hash intersection used,

2 some numbers:

- heavy hitter on 50% lists, i.e. $\alpha = 0.5$
- $m = 1024$, i.e. each server holds 1024 names
- $k = 32$, the size of random sublists

then

- a heavy hitter on ≈ 0.0078 intersection lists
- an honest user on ≈ 0.00000003 approximation list



Phase 2

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Epidemic process

PUSH, r_1 rounds: during a round each node that holds a non-empty intersection list chooses another node uniformly at random and sends there its intersection list.

PULL, r_2 rounds: during a round a node having an empty intersection list asks a node chosen uniformly at random for its intersection list. If the answer is a non-empty list, the asking node takes it.

r_1 and r_2 must be carefully chosen



Phase 3

voting

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algorithm

- 1 each node asks c random nodes for their short lists
 - 2 only a node on majority of these lists considered as heavy hitter
- trade-off between false (positives, negatives) and communication
 - c must be carefully chosen



Evaluation

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HH	r_1	r_2	il_1	il_2	il_3	CC	len_{il}
0	4	3	1.5%	84.8%	0.08%	$2.8 \cdot M$	1.05
0	5	2	1.5%	83.1%	0.12%	$2.3 \cdot M$	1.06
0	6	1	1.5%	80.0%	0.23%	$2.2 \cdot M$	1.07
1	4	3	2.3%	93.6%	37.6%	$2.7 \cdot M$	1
1	5	2	2.3%	92.0%	43.5%	$2.4 \cdot M$	1
1	6	1	2.3%	89.0%	53.2%	$2.7 \cdot M$	1
5	4	3	5.3%	99.7%	70.7%	$2.6 \cdot M$	1.4
5	5	2	5.3%	99.3%	84.7%	$3.3 \cdot M$	1.9
5	6	1	5.3%	98.0%	92.2%	$5.4 \cdot M$	2.8
100	4	3	52.1%	100%	97.7%	$24.9 \cdot M$	15
100	5	2	52.1%	100%	99.8%	$56.9 \cdot M$	40
100	6	1	52.1%	100%	99.9%	$114.1 \cdot M$	67

$M = 2^{19}$, $m = 512$, $k = 16$, $\alpha = 0.5$, $c = 5$, HH=the number of heavy hitters, r_1 and r_2 = numbers of rounds in Phase 2, il_j =fraction of servers with a nonempty intersection list after phase j , CC=communication complexity of 2nd phase and len_{il} =the average size of intersection lists



Attacks

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Security

- 1 changing the lists on a limited number of peers does not change the result of the algorithm
- 2 no single point of failure



Final remark

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Hash intersection

after some tuning it improves the algorithm presented at
ACNS'2009 just two weeks before in Paris



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Thank you for your attention!