

# Distributed Computing

## PWr, WIT, 2021

Prof. Mirosław Kutylowski

**2- BFS and spanning tree**

# Broadcasting to the whole network

## Message complexity:

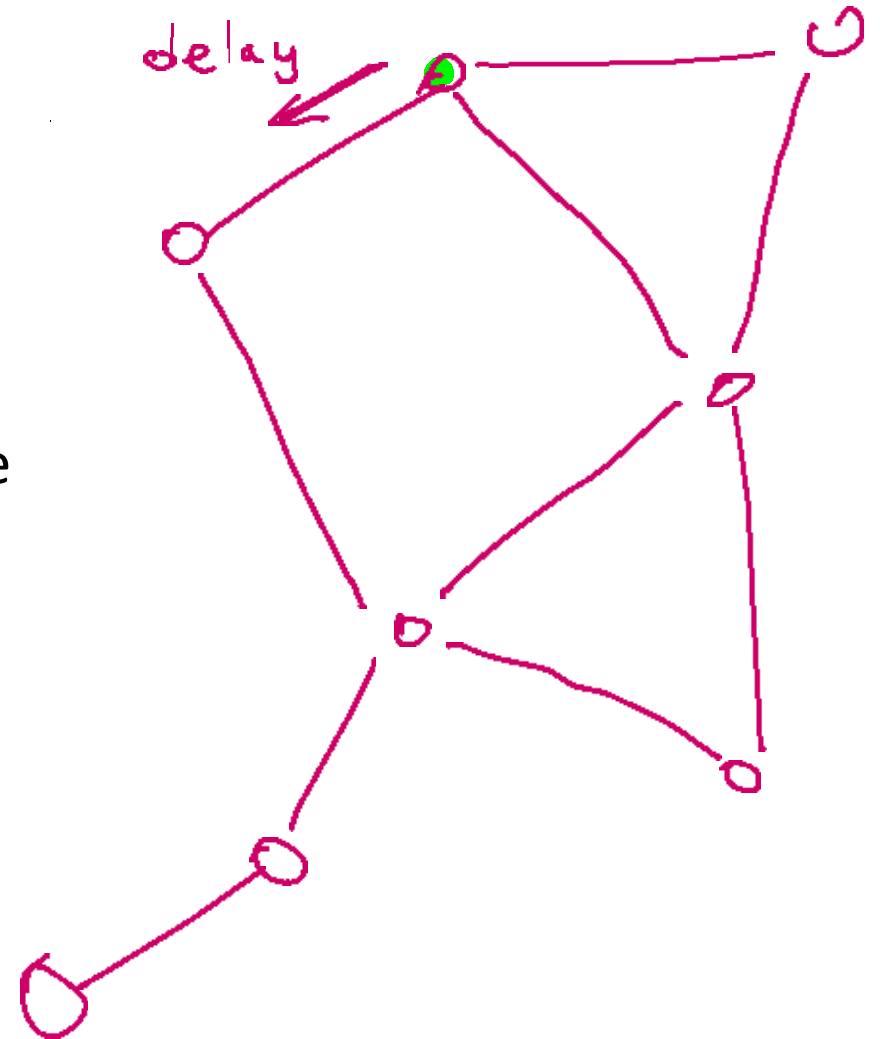
The total number of messages sent

## Time complexity

time needed so that all nodes get the message

## Assumptions:

- asynchronous, *global* no clock
- architecture unknown



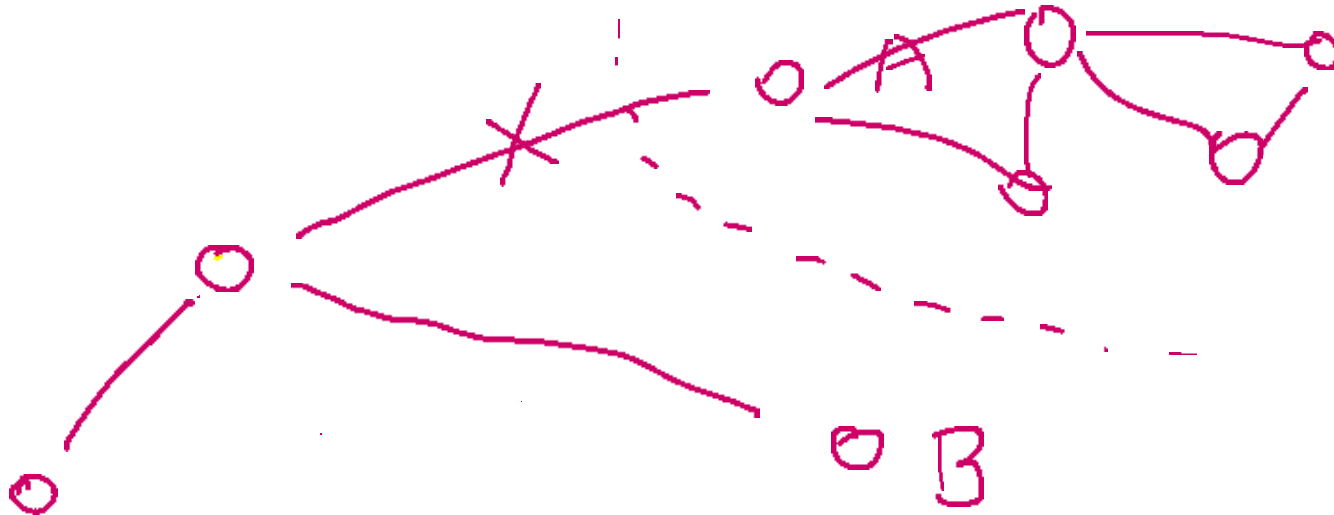
# Broadcasting by flooding

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## Algorithm 2.9 Flooding

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- 1: The source (root) sends the message to all neighbors.
  - 2: **Each other node**  $v$  upon receiving the message the first time forwards the message to all (other) neighbors.
  - 3: Upon later receiving the message again (over other edges), a node can discard the message.
- 



# Flooding

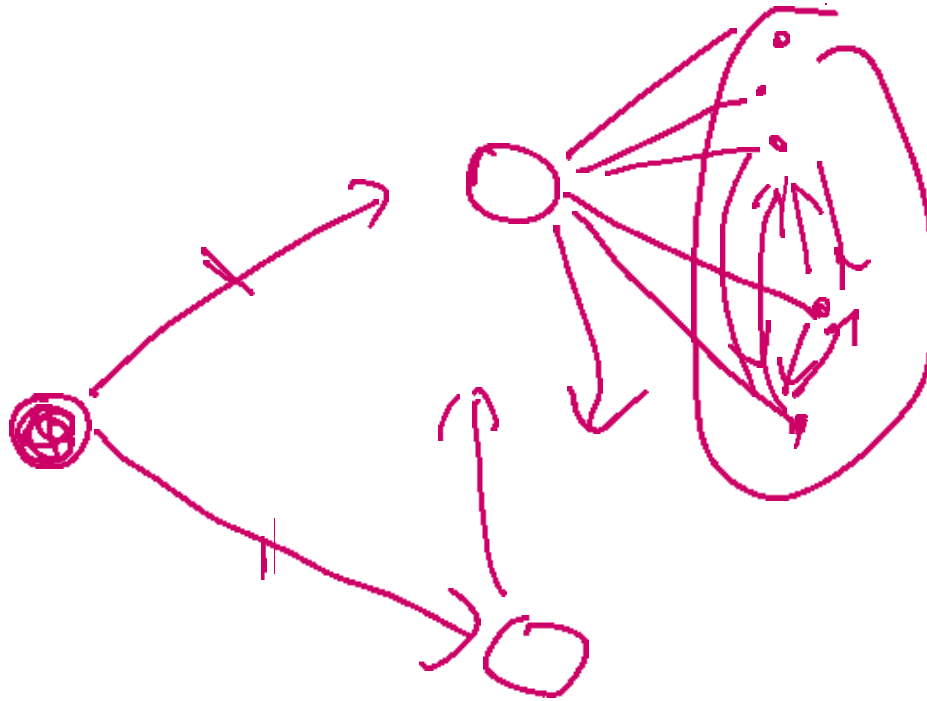
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~~Problem: message complexity~~



# Flooding

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Problem: message complexity

każda krawędź użyta

$\Rightarrow$  złożoność =  $\#$  ~~wierzchołków~~ krawędzi

# Flooding

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## Algorithm 2.9 Flooding

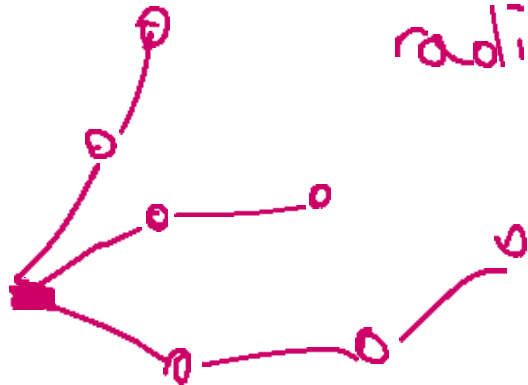
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Problem: ~~message~~ <sup>time</sup> complexity

$C_{2025} = \text{size of graph}$

radius



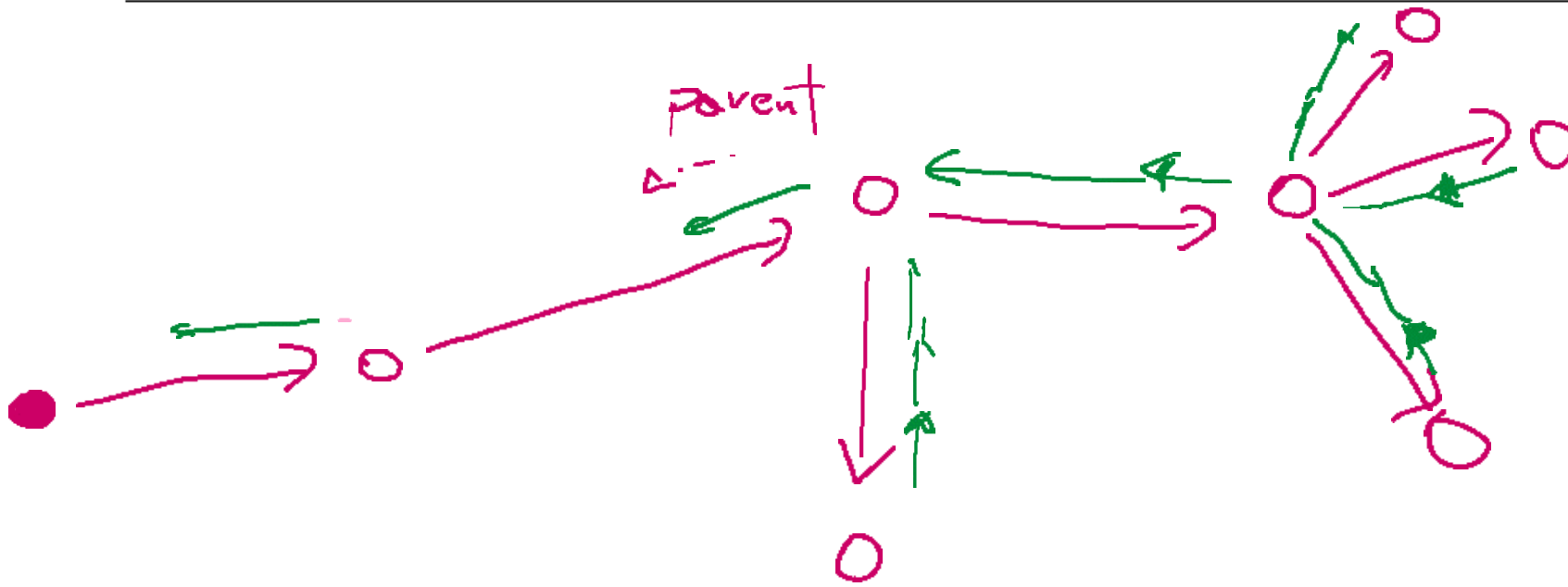
# Echo

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## Algorithm 2.10 Echo

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- 1: A leaf sends a message to its parent.
  - 2: If an inner node has received a message from each child, it sends a message to the parent.
- 



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# Bellman-Ford BFS (broad first search)

Find the shortest paths to the root

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## Algorithm 2.13 Bellman-Ford BFS

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- 1: Each node  $u$  stores an integer  $d_u$  which corresponds to the distance from  $u$  to the root. Initially  $d_{\text{root}} = 0$ , and  $d_u = \infty$  for every other node  $u$ .
  - 2: The root starts the algorithm by sending “1” to all neighbors.
  - 3: **if** a node  $u$  receives a message “ $y$ ” with  $y < d_u$  from a neighbor  $v$  **then**
  - 4:   node  $u$  sets  $d_u := y$
  - 5:   node  $u$  sends “ $y + 1$ ” to all neighbors (except  $v$ )
  - 6: **end if**
-

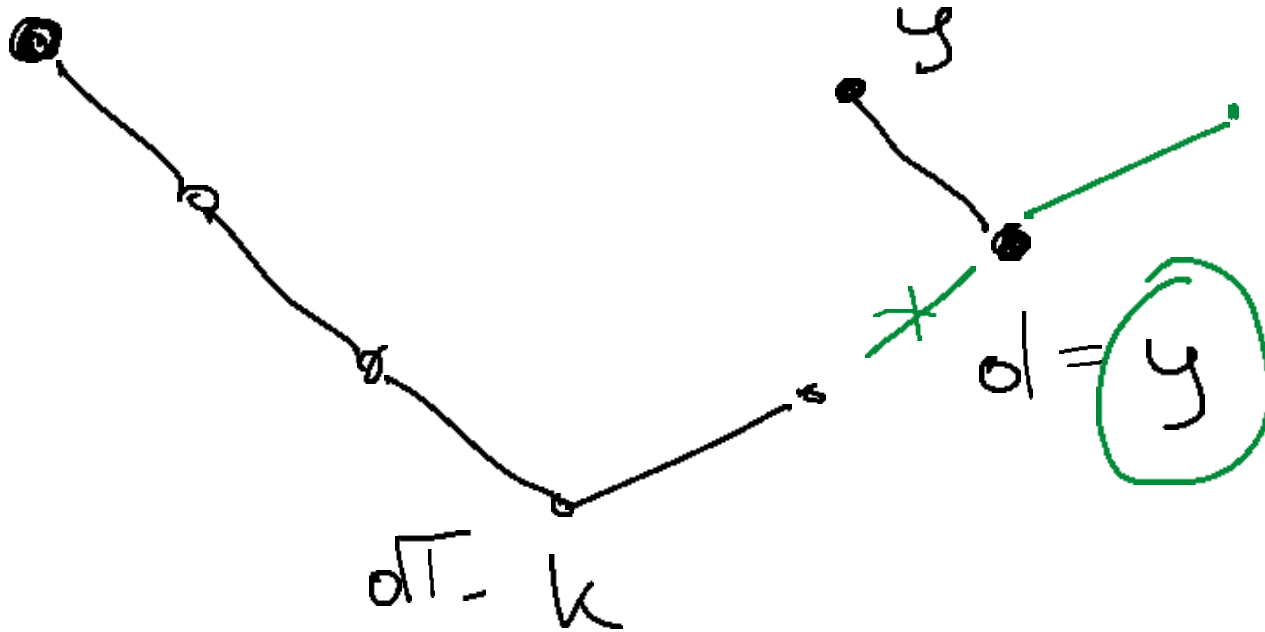
# Bellman-Ford

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$$y < k$$

# Bellman-Ford

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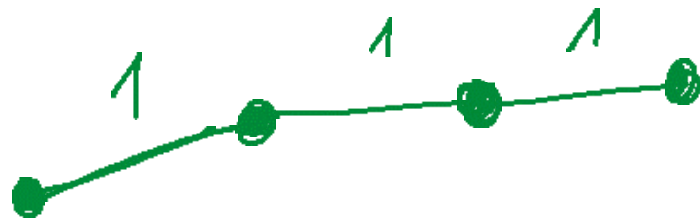
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For a graph with diameter  $D$ , the number of edges  $m$ , and  $n$  nodes:

Time complexity  $O(D)$

Message complexity  $O(mn)$

time for 1 message:  $\in [0, 1]$



# Bellman-Ford

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## Algorithm 2.13 Bellman-Ford BFS

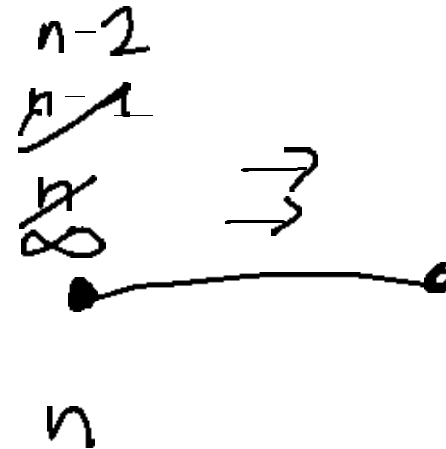
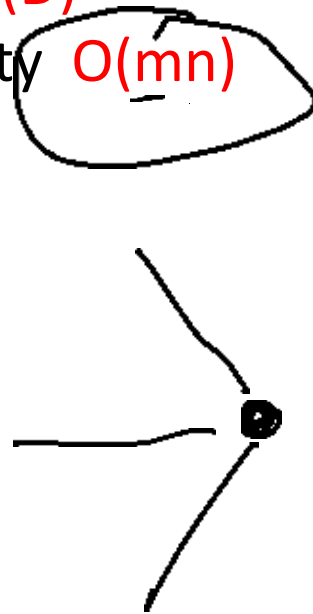
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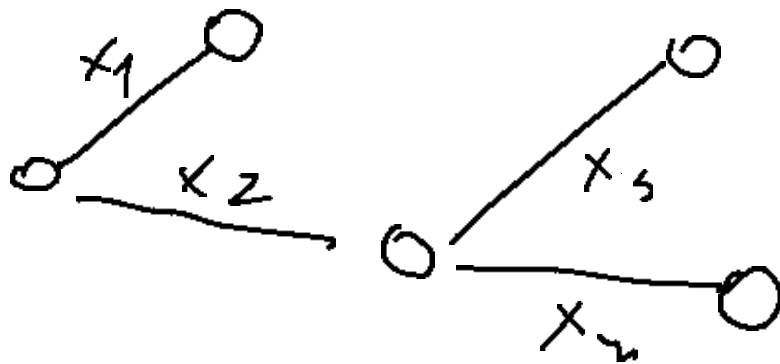
Time complexity  $O(D)$

Message complexity  $O(mn)$



# Minimum Spanning Tree

- A tree containing each node of the graph
- Each edges has a weight
- The sum of weights in the tree should be minimum possible



$$\sum x_i = \text{minimized}$$

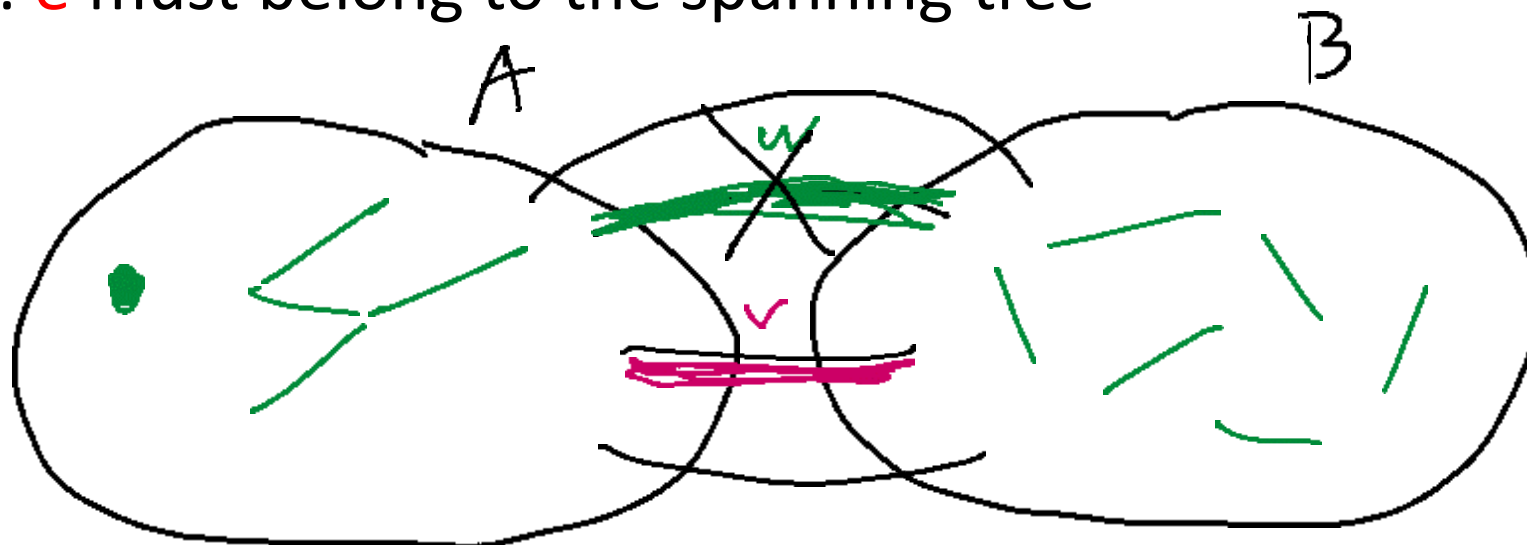
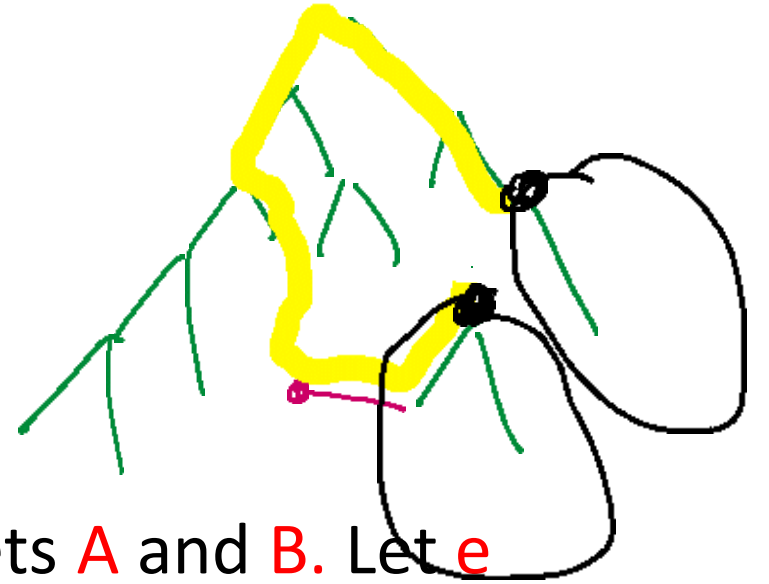
# MST- key observation

## Theorem

*Assume: the weights are different*

Partition the nodes of the graph into disjoint subsets **A** and **B**. Let **e** be the lightest edge connecting **A** and **B**

then: **e** must belong to the spanning tree



$v < w$   
 $\Rightarrow$  spans

# MST

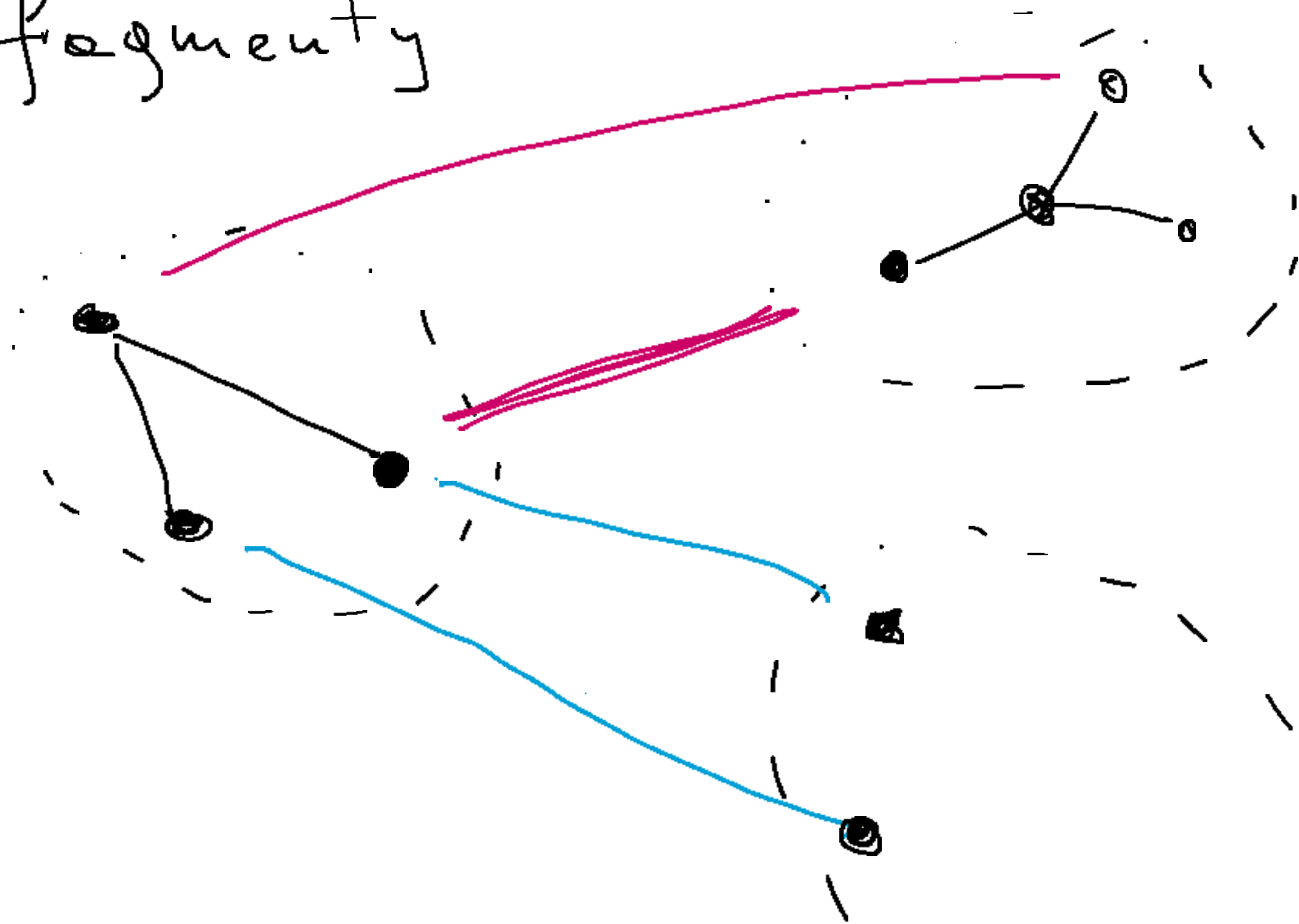
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**Algorithm 2.18** GHS (Gallager–Humblet–Spira)

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- 1: Initially each node is the root of its own fragment. We proceed in phases:
  - 2: **repeat**
  - 3: All nodes learn the fragment IDs of their neighbors.
  - 4: The root of each fragment uses flooding/echo in its fragment to determine the blue edge  $b = (u, v)$  of the fragment.
  - 5: The root sends a message to node  $u$ ; while forwarding the message on the path from the root to node  $u$  all parent-child relations are inverted {such that  $u$  is the new temporary root of the fragment}
  - 6: node  $u$  sends a merge request over the blue edge  $b = (u, v)$ .
  - 7: **if** node  $v$  also sent a merge request over the same blue edge  $b = (v, u)$   
**then**
  - 8:     either  $u$  or  $v$  (whichever has the smaller ID) is the new fragment root
  - 9:     the blue edge  $b$  is directed accordingly
  - 10: **else**
  - 11:     node  $v$  is the new parent of node  $u$
  - 12: **end if**
  - 13: the newly elected root node informs all nodes in its fragment (again using flooding/echo) about its identity
  - 14: **until** all nodes are in the same fragment (i.e., there is no outgoing edge)
-

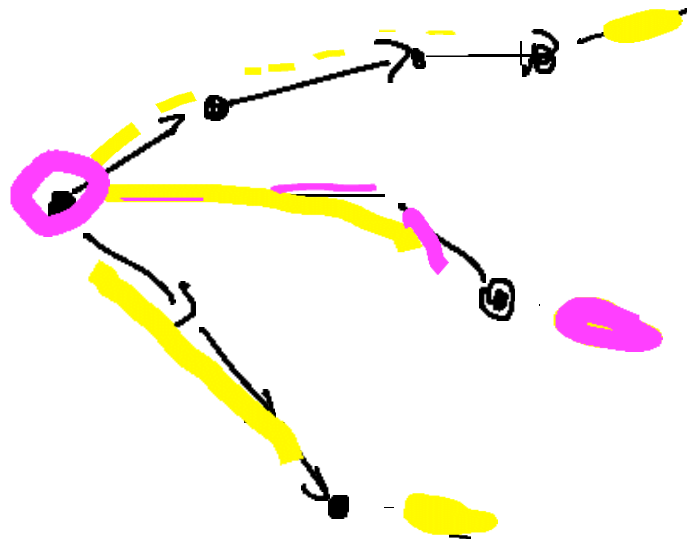
fragmenty





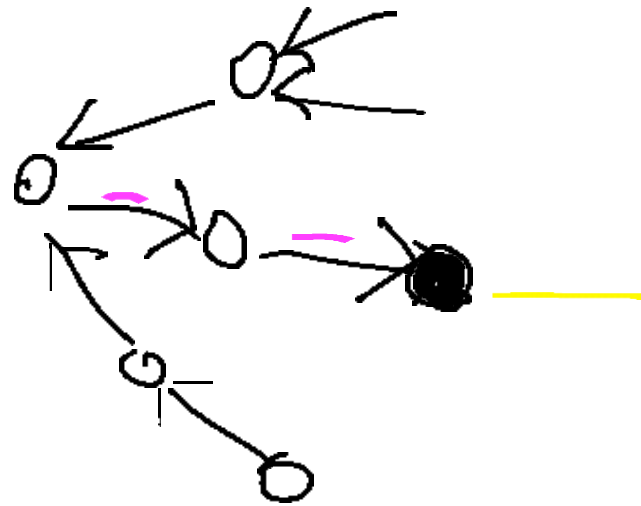
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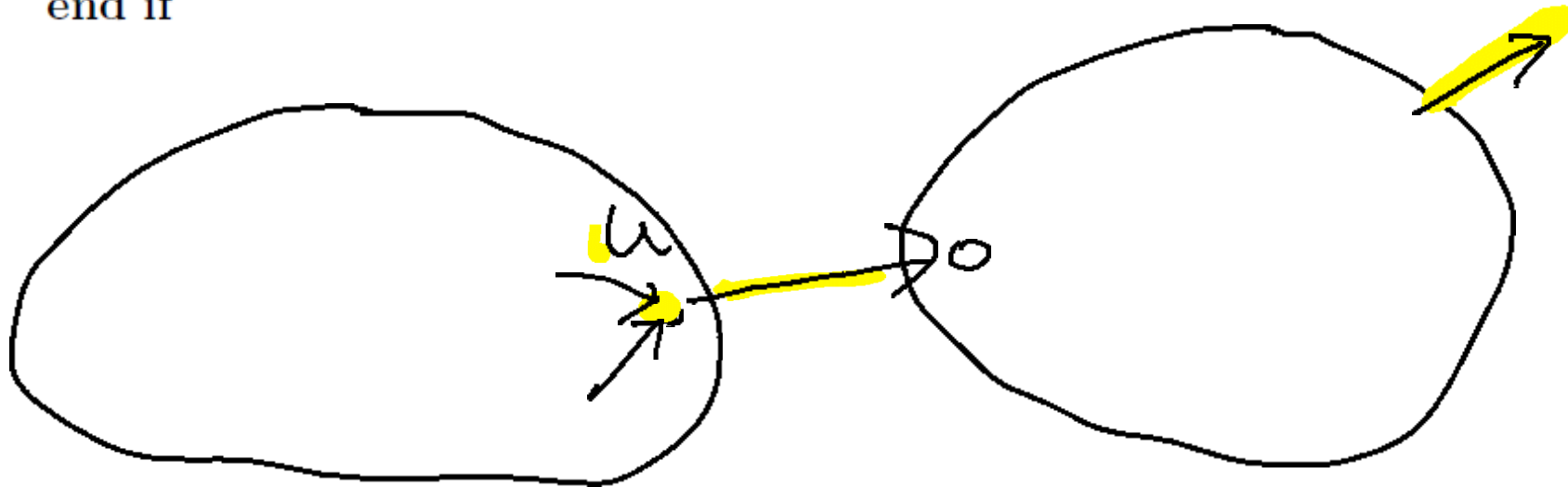
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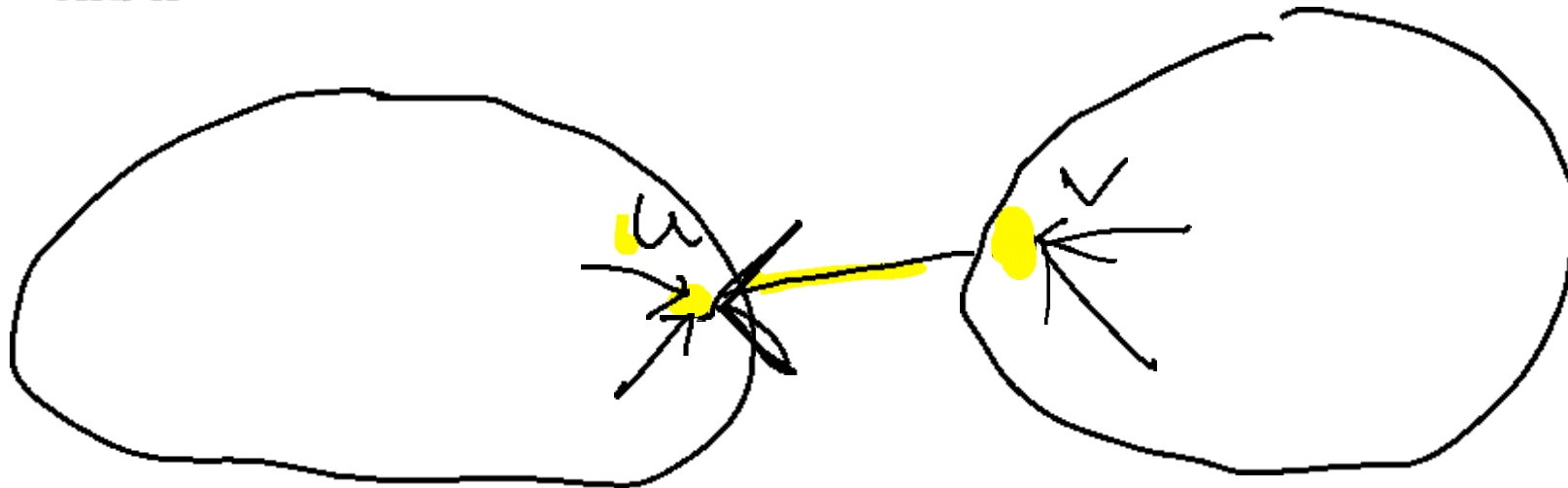
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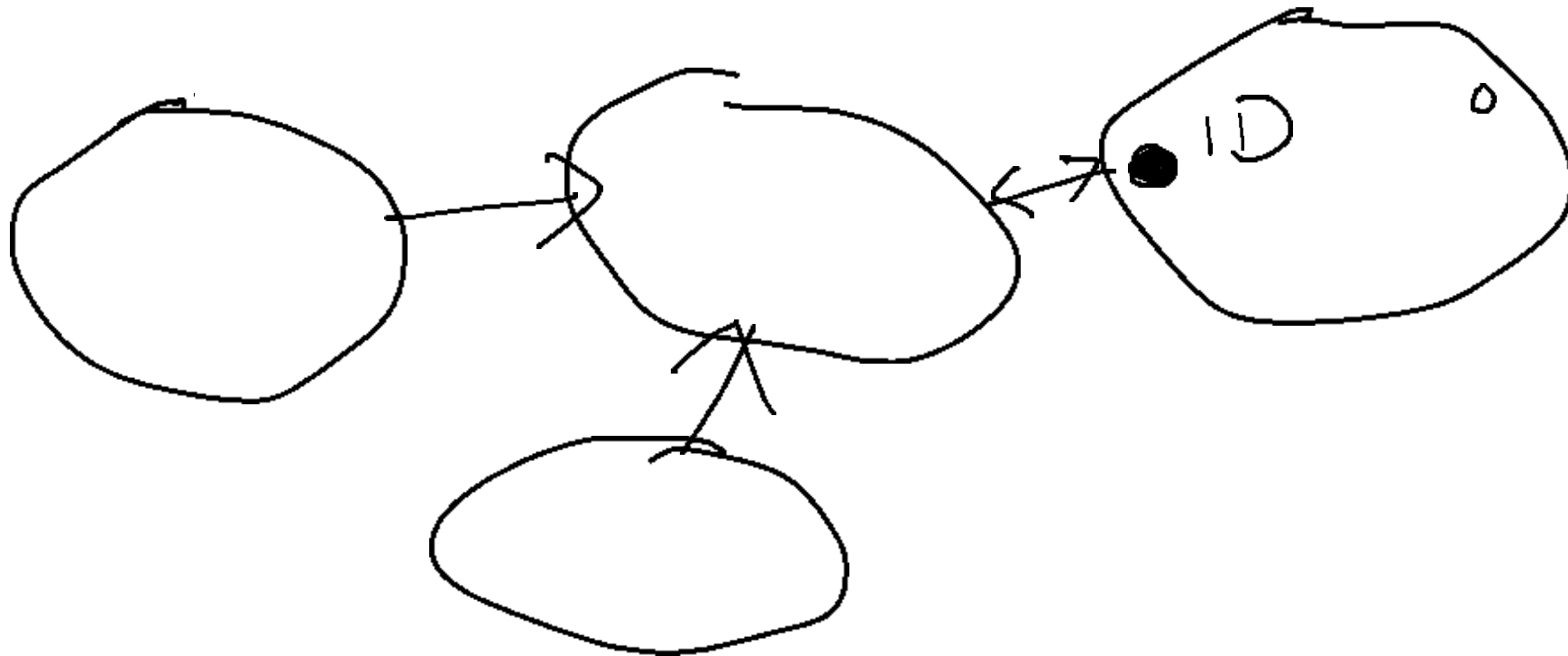
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złożoność: czasowa

1 runda:  $\text{time} = O(\text{średnica fragmentu})$   
 $\leq D$

# rund ?

$k$  fragmentów  $\xrightarrow{\text{runda}}$   $\leq \frac{k}{2}$  fragmentów

# rund  $\in \log(n)$

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